



Sheet 1 of 2

LIST OF REFERENCES CITED BY APPLICANT				ATTY. DOCKET NO. VTE-152-B		SERIAL NO. 10/817,511	
				APPLICANT John Bugel			
				FILING DATE April 2, 2004		GROUP 3475	
U. S. PATENT DOCUMENT							
EXAMINER INITIALS		PATENT NO.	ISSUE DATE	PATENTEE	CLASS	SUBCLASS	FILING DATE
/FDL/	AA	6,523,451	02-25-2003	Liao et al.			
/FDL/	AB	6,234,060	05-22-2001	Jolly			
/FDL/	AC	5,881,767	03-16-1999	Loser			
/FDL/	AD	5,431,086	07-1995	Morita et al.			
/FDL/	AE	5,271,226	12-21-1993	Stone	↓	↓	
	AF						
FOREIGN PATENT OR PUBLISHED PATENT APPLICATION							
		DOCUMENT NO.	PUBLICATION DATE	COUNTRY OR PATENT OFFICE	CLASS	SUBCLASS	TRANSLATION
/FDL/	AL	GB2203195A	10-1988	UK	↓	↓	
/FDL/	AM	DE 101 222 97C1	06-2002	Germany	↓	↓	
/FDL/	AN	EP 1 391 647	06-17-2003	Europe	↓	↓	
/FDL/		DE 199 12 334 A1	09-28-2000	Germany	↓	↓	
OTHER REFERENCES (including Author, Title, Date, Pertinent Pages, etc.)							
		Kenji Okiyama and Ken Ichijou; STUDY OF PNEUMATIC MOTION BASE CONTROL CHARACTERISTICS; Tokyo University of Technology →					
		Karim Khayati, Pascal Bigras, and Louis-A. Dessaint; NONLINEAR CONTROL OF PNEUMATIC SYSTEMS; Ecole de Technologie Supérieure; 1100, rue Notre-Dame Ouest, Montreal (Quebec) H3C 1K3 →					
/FDL/	AO	HIGH SPEED SERVO PNEUMATIC ACTUATOR SYSTEMS; (modified on 13 January 2004); Design of High Speed Machinery (DHSM) LINK Programme; Engineering & Physical Sciences Research Council; Department of Trade & Industry; March 1995 to August 1997, Grant Reference: GR/K38663					
	AP	Journal of Zhejiang University SCIENCE; (ISSN 1009-3095, Monthly), 2001 vol. 2, no. 2, pages 128-131; CLC Number: TP271, 32; Document Code: A; RESEARCH ON THE CONTINUOUS POSITIONING CONTROL TO SERVO-PNEUMATIC SYSTEM; Tao Guo-liang, Wang Xuan-yin, & Lu Yong-xiang					
/FDL/	AR	MODELING AND SIMULATION OF A SERVOPNEUMATIC GRIPPER; Salvador Esque and Jose LM Lastra, date 10 Dec 99					
	AS	MODIFIED FEEDBACK LINEARIZATION CONTROLLER FOR PNEUMATIC SYSTEM WITH NON-NEGLIGIBLE CONNECTION PORT RESTRICTION; Pascal Bigras, Karim Khayati, Tony Wong; University of Quebec					
/FDL/	AT	ND9000 INTELLIGENT VALVE CONTROLLER; METSO AUTOMATION; date: July 7/2003					
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EXAMINER /F. Daniel Lopez/ (11/26/2007)				DATE CONSIDERED			
EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609; Draw line through citation if not considered. Include a copy of this form with next communication to applicant.							

FORM PTO-1449		ATTY. DOCKET NO. VTE-152-B	SERIAL NO. 10/817,511
LIST OF REFERENCES CITED BY APPLICANT		APPLICANT John Bugel	
		FILING DATE April 2, 2004	GROUP 3745
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/FDL/	AF	INTRODUCING PRECISIONAIRE - A BREAKTHROUGH PNEUMATIC MOTION SYSTEM	
	AG	AXIS CONTROLLER SPC 200; Festo AG&Co.; Products 2001	
	AH	KUHNKE "SPEEDY" Machine Building Process Module; Switched Pneumatic Electrical Endposition Damping- E635 GM/02 92.652	
	AI	SWITCHED PNEUMATIC ELECTRICAL ENDPOSITION DAMPING; Werner Brockman; University of Lubeck Institute of Computer Engrg. Lubeck, Germany	
/FDL/	AJ	BLOCK-ORIENTED NONLINEAR CONTROL OF PNEUMATIC ACTUATOR SYSTEMS; fulin Xiang; Doctoral Thesis, Mechatronics Lab, Department of Machine Design, Royal Institute of Technology, KTH; S-100 44, Stockholm, Sweden, 2001.	
	AK	HYDRAULIC & PNEUMATIC ACTUATORS; Sensors & Actuators for Mechatronics Hydraulics and Pneumatic Actuators; K. Craig.	
	AL	ADAPTIVE NEURON CONTROL BASED ON PREDICTIVE MODEL IN PNEUMATIC SERVO SYSTEM; Huang Wenmei, Yang Yong, Tang Yali; College of Mechanical and Automotive Engrg. Hunan University, 410082, Changsha, Hunan, P.R. China.	
	AM	PROPNEU - AN INTELLIGENT SOFTWARE TOOL; Hong Zhou, Ph.D., Festo AG & Co., Ruitersstr, 82, D-73734, Esslingen, Germany	
	AN	PNEUMATIC SERVO SYSTEMS CONTROLLED BY SELF-TUNING FUZZY RULES; Akira Shimizu, Satoru Shibata, and Mitsuru Jindai, Dept. of Mech. Eng. Ehime University, 3, Bunkyo-cho, 790-8577, Matsuyama, Ehime, Japan.	
/FDL/	AO	MODELICA - Proceedings of the 3 rd International Modelica Conference, Linkoping, November 3-4, 2003, Peter Fritzson (editor)	
/FDL/	AP	HIGH STEADY-STATE ACCURACY PNEUMATIC SERVO POSITIONING SYSTEM WITH PVA/PV CONTROL AND FRICTION COMPENSATION; Shu Ning and Gary M. Bone; Dept. of Mechanical Engrg., McMaster University, Hamilton, Ontario, Canada, L8S 4L7. Proceedings of the 2002 IEEE, International Conference on Robotics & Automation, Washington, DC - May 2002	
	AR	A HYBRID PNEUMATIC/ELECTROSTATIC MILI-ACTUATOR; Kenneth H. Chiang, Ronald S. Fearing; ROBOTICS AND INTELLIGENT MACHINES LABORATORY; Dept. of Electrical Engrg. And Computer Sciences; 265M Cory Hall, University of California, Berkeley, CA 94720-1770	
	AS	MODELING IDENTIFICATION, AND CONTROL OF A PNEUMATICALLY ACTUATED, FORCE CONTROLLABLE ROBOT; J.E. Bobrow and B.W. McDonnell, Irvine, California 92697	
	AT	MODELLING AND SIMULATION OF PNEUMATIC CYLINDERS FOR A PHYSIOTHERAPY ROBOT; R. Richardson, A.R. Plummer, M. Brown; School of Mechanical Engrg., University of Leeds, UK; Inetron Ltd, UK	
EXAMINER		DATE CONSIDERED	
/F. Daniel Lopez/ (11/26/2007)			
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All lined through references have not been considered, since they do not list a date associated with the reference. This consideration of the IDS supersedes the previous listing.